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This manual contains solutions to the exercises presented in Introduction to Continuum Mechanics (Cambridge University Press). There are over one hundred and fifty exercises and their solutions in the following chapters. I have included the exercises for the convenience of instructors who would

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 $dx(1)(1)-dx(2) = dx \cdot dx(2)\cos\theta = dX \cdot 2\epsilon \cdot dX(2)(4.7-11)$ where θ is the angle between the deformed vectors as shown in Figure 4.3. If now we let ϵ , the angle measures the small change in the original right angle between $dX(1)$ and $dX(2)$ and also $\cos\theta = \cos = \sin \approx$ since is very small for infinitesimal deformations.

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